

A Low-cost Life Sign Detection Method based on Time Series Analysis of Facial Feature Points

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Abstract: The use of image based presentation attack detection (PAD) systems has experienced an enormous growth of interest in recent years. The most accurate techniques in literature addressing this topic rely on the verification of the actual three-dimensionality of the face, which increases complexity and costs of the system. In this work, we propose an effective and low-cost face spoofing detector system to supplement a PPGI-based vital signal monitoring application. Starting from a set of automatically located facial feature points, the movement information of this set of points was obtained. Based on a time series analysis of the landmark position distances using peak descriptors and cross-correlation coefficients as classifiers in a sliding window, life signs have been exploited to develop a system being able to recognize false detections and biometric spoofs. To verify the performance, experiments on three different benchmark datasets (CASIA face anti-spoofing, MSU and IDIAP Replay-Attack databases) were made. The evaluation of the proposed low-cost approach showed good results (accuracy of ~85-95%) compared to more resource-intensive state-of-the-art methods.

1 INTRODUCTION

Automatic face recognition and tracking systems are nowadays widely used in many different applications, such as de-duplication of identity, authentication of mobile payment or people analytics and people flow management. Particularly, in our case, human faces are detected and tracked to perform camera based heart rate estimation based on the Photoplethysmography Imaging (PPGI) method. Using an off the shelf camera under ambient light the systems allows an online beat-to-beat heart rate estimation from a person's forehead (Bloecher et al., 2014). However, such face recognition based systems are vulnerable to spoof attacks made by non-real faces, for instance facial pictures such as portrait photographs. In our case, this may lead to the unwelcome effect that the system tries to extract vital signs of non-real persons. Therefore, face recognition based systems need presentation attack detection (PAD) in order to guard against spoofing or false detections. In the literature many approaches utilize Face Liveness Detection for PAD (Kähm and Damer,

2011), (Parveen, 2015), (Garud and Agrawal, 2016). Some of the most interesting methods include:

- *Life sign.* Exploit inherent characteristics of a live face, e.g. eye blinking (Pan et al., 2007) or demand real time responses from the user, e.g. smile detection (Deniz et al., 2008)
- *Frequency and texture.* Differentiate between real and fake in terms of shape and detailedness, using feature extraction and classifiers. Examples include algorithms based on frequency analysis of face images (Kim et al., 2012) or the extraction of micro textures (Maatta et al., 2011).
- *Motion.* Approaches based on foreground and background motion correlation using optical flow (Anjos et al, 2014).

For our purpose, an effective and low-cost detection method was favoured, in order to save computational resources needed for other parts of our heart rate extraction algorithm. Especially since we aim for a vital sign extraction solution for embedded and mobile devices in the future.

Regarding the three mentioned methods, the life sign based face liveness detection for PAD is known for being highly secure against 2D image or 3D sculpture spoof attacks (Chakraborty and Das, 2014), while it does not require the use of highly complicated and expensive devices. While other approaches show better resistance to video replay attacks, this was not focused in our system, due to the fact that the user could be interested on vital sign detection in videos. Furthermore the combination of life sign and vital sign detection may uncloze further interesting applications. These facts made life sign based PAD a promising solution for our system.

2 METHODS

In the present work, a new presentation attack method is proposed which is based on detection and tracking of a set of facial points and subsequent analysis and processing of the aforementioned data in order to detect life sign patterns.

2.1 Facial Feature Detection

The set of facial landmarks are automatically detected and tracked using the *IntraFace* software (Xiong and De la Torre, 2013), which is a free research software for facial image analysis. Facial feature detection and tracking are performed based on the supervised decent method (SDM). It can be used to track a total of 49 facial points, providing the current landmark locations in the image: 10 for the eyebrows, 12 for the eyes, 9 for the nose and 18 for the lips (see Figure 1).

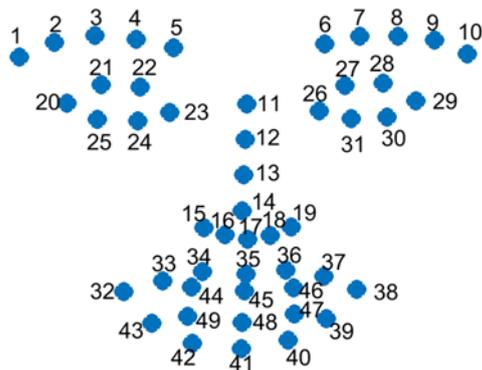


Figure 1: Set of 49 facial landmarks of the IntraFace tracker.

2.2 Analysis of the Feature Points

A time series analysis of the position of the facial feature points showed clear differences in the change of landmark positions depending on a facial gesture.

Those relative distance changes between the landmarks were not found during measurements of moving portrait pictures. As it can be seen in Figure 2, there were several peaks and patterns that could be used to build a PAD program.

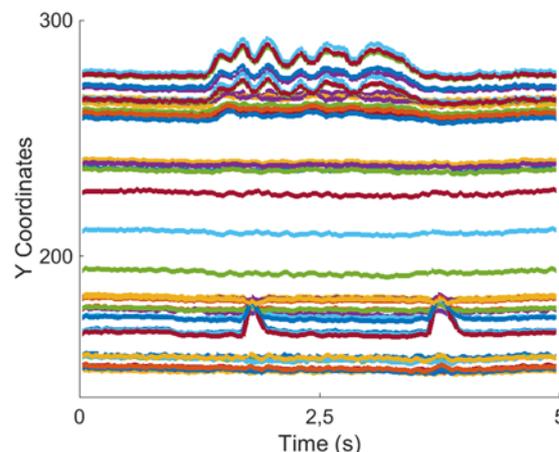


Figure 2: Y coordinates of all 49 points during a time interval of 5 seconds in a face video taken with 30 fps.

3 PROPOSED ALGORITHM

Analysing the time series of the relative distance changes of the feature locations, different facial expression dynamics were detected. Specifically, the selected life signs were blinking, speaking, smiling, mouth movements and eye movements. As it is observed in Figure 6, the life signs have a varying time series dynamic, so different techniques were used to detect each of them. The resulting algorithms were implemented in MATLAB.

3.1 Blinking

Blinking is a semi-autonomic rapid closing of the eyelid. Generally, between each blink, there is an interval of 2–10 seconds; actually rates vary by individual averaging around 10 blinks per minute in a laboratory setting (Bentivoglio et al, 1997). Therefore, it was considered reasonable choosing a time interval of 5 seconds for the time series analysis.

During this interval, the distances between the feature points of the upper and downer-eye are analysed for both eyes (see Figure 3). If the eye closes, the distance between the upper and downer-eye points decreases. The result is a signal peak (as seen in Figure 8a). Before classification, the eye distance signals are normalized using the nose distances (features 11 and 14). As classifier we use a peak descriptor, combining height and width of the

peak. As a blink lasts for about 0.1 to 0.2 seconds (Bentivoglio et al, 1997), the peak width needs to be less than 8 frames (~0.25s) and the normalized peak height smaller than a threshold value of '0.3'. Secondary a peak has to be detected for all four eye-distances.

In addition to its substantial contribution for PAD, blinking rate detection can provide important information towards the measure of a person's tiredness as a further parameter for psycho-physiological state estimation. For this reason the performance will be separately considered in chapter 5.

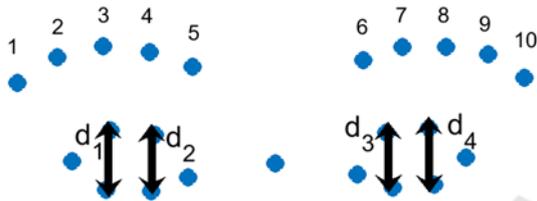


Figure 3: The four eye distances used for the blinking detection algorithm.

3.2 Speaking and Smiling

In order to detect whether the user speaks or smiles, the cross-correlation of the mouth feature distance signals was used as classifier (see Figure 8 b-c). Two different signals were considered: Inner-outer mouth distances and nose-mouth distances.

The distance between the three inner-mouth and outer-mouth points is computed for each frame. The resulting signal is analysed using cross-correlation. The coefficients $R_{d_{11} d_{12}}$, $R_{d_{12} d_{22}}$, $R_{d_{31} d_{32}}$ (see Figure 4) are computed for a sliding time window of 5 seconds. If a person speaks or smiles, the inner and outer signals will show similarity whereby the cross-correlation coefficient will have high values.

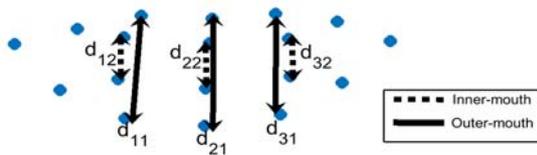


Figure 4: The three pair mouth distances used for the speaking and smiling detection algorithm.

Secondly, the cross-correlation between the nose-mouth distances was also computed for all four central mouth features. In the event of speaking or smiling, d_1 & d_2 will decrease and d_3 & d_4 will increase. Thus, the correlations coefficients of the distance signals $\langle d_1, d_3 \rangle$, $\langle d_1, d_4 \rangle$, $\langle d_2, d_3 \rangle$ and $\langle d_2$ -

$d_4 \rangle$ are supposed to have small values. Empirical tests proved a cross-correlation coefficient of the inner-outer mouth distances higher than '0.8' and a cross-correlation of the nose-mouth distances smaller than '0.85' to be proper values for the speak and smile detection.

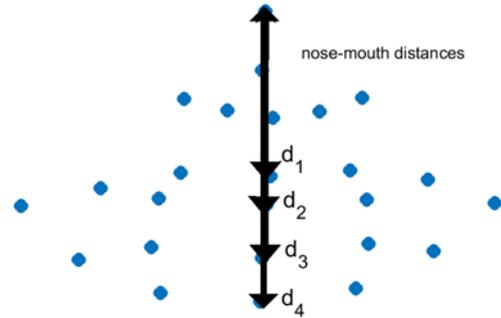


Figure 5: The four nose-mouth distances used for the speak and smile detection algorithm.

3.3 Mouth Movements

In addition to speaking or smiling, buccal motions can occur while the mouth is closed. In this case, the outer lower-nose part will move analogous to the mouth, while the upper-nose part is likely to remain still. Exploiting this idea, the x coordinates of three features were tracked in each side of the face. Based on that the cross-correlations coefficients $R_{XR3 XR1}$, $R_{XR3 XR2}$, $R_{XL3 XL1}$ and $R_{XL3 XL2}$ were computed as further classifiers (Figure 6). Empirical analysis showed, that feature position changes in the mouth area can be considered as life sign 'mouth-movement', when the cross-correlation coefficient of the upper-nose-mouth signals is lower than '0.7' and the coefficient of the lower-nose-mouth signals is above '0.9'.

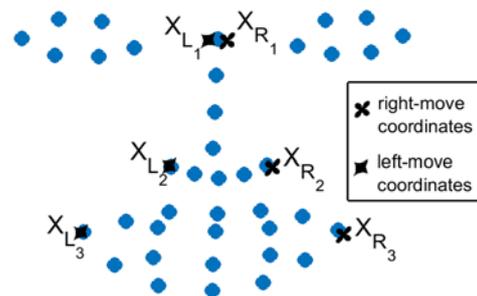


Figure 6: Three pairs of facial feature points used for the mouth movement detection algorithm.

3.4 Eye Movements

Similar to the mouth movements, eye movements

may occur even if the user does not blink, e.g. due to a change in the eye direction. To take this into account, the outer eye distances were determined as the distances between the upper inner-eye and the central eyebrow features. Based on that, the cross-correlation coefficients between the inner-eye and the inverse of the outer-eye distances were computed to detect ‘eye movement’ life signs (see Figure 7).

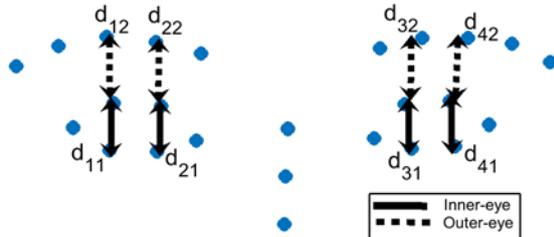


Figure 7: The four eye pair distances used for the eye movement detection algorithm.

3.5 Classification

The classifiers, including the peak descriptor and the cross-correlation coefficients, were analysed using a sliding time window of 5 seconds. If one classifier met the realness criteria, e.g. in form of exceeding the correlation coefficient threshold, the face in the image was classified as real.

4 PERFORMANCE EVALUATION

The performance of the proposed liveness detection scheme was validated on two different phases: Firstly, a particular test was performed to measure the accuracy of the eye blink detection scheme as already mentioned in section 3.1. Secondly, the general performance of the life sign based anti-spoofing system was tested.

4.1 Evaluating Performance of the Blink Detector

4.1.1 Evaluation Tools

To measure the eye blink detector’s accuracy, predicted blinks are compared to the ground-truth blinks. The correctly detected eye-blinks are denoted as True Positives (TP), the correctly detected non-blinks are denoted as True Negatives (TN), false detections are denoted as False Positives (FP), and missed eye-blinks are denoted as False Negatives (FN). Based on these parameters four common measures of the system performance were used:

$$\text{Precision} = \frac{TP}{TP + FP} \quad (1)$$

$$\text{Recall} = \frac{TP}{TP + FN} \quad (2)$$

$$\text{FP Rate} = \frac{FP}{TN + FN} \quad (3)$$

$$\text{Mean Accuracy} = \frac{TP + TN}{TP + TN + FP + FN} \quad (4)$$

4.1.2 Databases

The performance of the proposed blink detection scheme was validated on two different databases: *Talking Face Video* and *ZJU*.

The *Talking Face video dataset* consists of 5000 frames taken from a video of a person engaged in conversation (PRIMA; 2000). This corresponds to about 200 seconds of recording with a total of 61 eye blinks. The sequence was taken as part of an experiment designed to model the behaviour of the face in natural conversation. Ground truth information for all eye blinks in the *Talking Face Video* was obtained as part of the PRE-WORK project (Divjak and Bischof, 2009) at the Graz University of Technology, Austria. For each blink the type (full or partial), start index, peak index and stop index were annotated. An eye blink is considered as detected, if there is a match between the detected blink frame and the annotation blink frame indexes. The results are presented in Table 1 and 2.

The *ZJU dataset* consists of 80 short videos (10876 frames) of 20 individuals with and without glasses captured with 30fps and size of 320×240 (Pan et al, 2007). The videos are collected from frontal and upward views. In sum the *ZJU* contains 255 eye blinks. The ground truth information was again obtained from the project of (Divjak and Bischof, 2009). The results are shown in Table 1 and 2. It should be mentioned that some of them are voluntary longer eye blinks. Therefore the FN increases slightly compared to the *Talking Face* dataset, since our algorithm only detects blinks with a maximum duration of 0.6 seconds.

Table 1: Confusion matrix results of the blink detector.

Database	TN	FN	FP	TP
Talking	4943	3	1	58
ZJU	11604	6	17	260

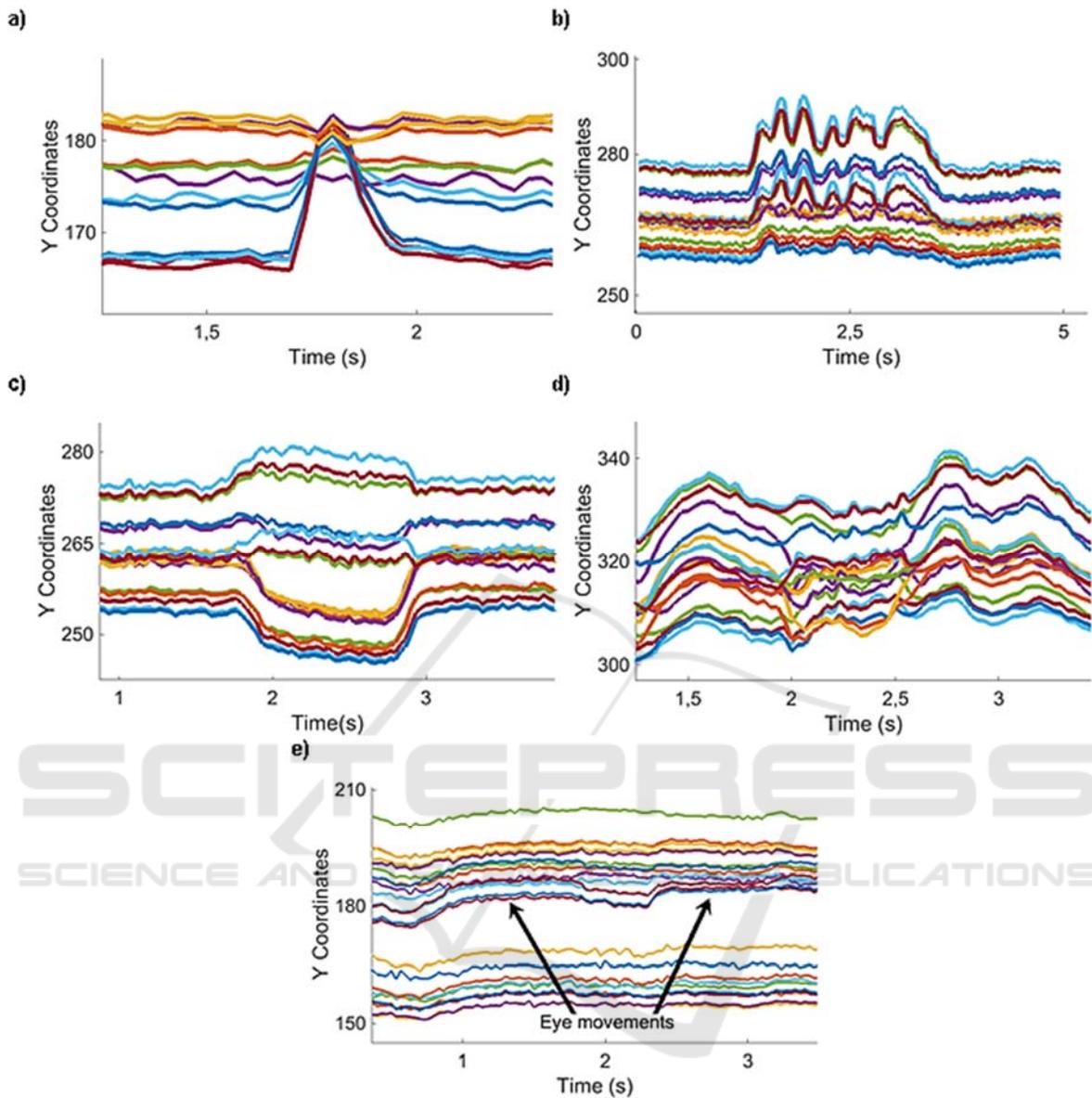


Figure 8: Time series analysis of the Y coordinates of the tracked facial feature points showing the following life signs: a) Blink; b) Speak; c) Smile; d) Mouth movements; e) Eye movements.

Table 2: Performance comparison of the blinking detection method.

Method	Database	Precision	Recall	FP Rate	Mean Accuracy
Divjak & Bischof	Talking	-	95,0%	19,00%	88,0%
Divjak & Bischof 2	Talking	-	92,0%	6,00%	93,0%
Lee et al.	Talking	83,3%	91,2%	-	-
Drutarovsky & Fogelton	Talking	92,2%	96,7%	0,10%	99,8%
Our method	Talking	98,3%	95,1%	0,02%	99,9%
Divjak & Bischof	ZJU	-	95,0%	2,00%	97,0%
Divjak & Bischof 2	ZJU	94,4%	91,7%	-	-
Lee et al.	ZJU	90,7%	71,4%	1,00%	94,8%
Drutarovsky & Fogelton	ZJU	91,0%	73,1%	0,17%	99,8%
Our method	ZJU	93,9%	97,7%	0,15%	99,8%

4.1.3 Comparison of Our Method

After testing the accuracy of our blink detector system, the proposed algorithm’s performance was compared to other methods in the literature. As it can be seen in Table 2, the proposed algorithm achieves good results and shows comparable or even better results than the state-of-the-art methods regarding the two standard datasets. For instance, the precision obtained with our approach is higher (around 6-7%) for the Talking a dataset. Moreover, the mean accuracy is comparable or slightly higher for both datasets.

4.2 Evaluating Performance of Liveness Detector

4.2.1 Evaluation Tools

Similar to the evaluation of the blink detection, the classical approach regards a PAD system as a binary classification system, but the metrics are ambiguous and not unified in several publications. Apart from the parameters already used for the blinking classification, the following new evaluating methodologies were included:

- Half Total Error Rate (HTER). A possible way to measure the detection performance is to use the *HTER*, which combines the FP Rate, also known as the False Rejection Rate (*FRR*), which is the ratio of incorrectly rejected genuine users, and *FN* Rate, also known as the False Acceptance Rate (*FAR*), implying the ratio of incorrectly accepted impostors and is defined in the formula 5:

$$HTER (\%) = \frac{FRR + FAR}{2} \quad (5)$$

- Detection-Error Trade-off (DET). DET curves are score distributions utilized to evaluate the anti-spoofing accuracy graphically. The DET plotting code was downloaded from (NIST, 2007).

4.2.2 Databases

The performance of the proposed liveness detection scheme was validated on three different databases: CASIA, MSU and IDIAP.

A) CASIA

This database mainly focuses on variation of the collected data, trying to provide a comprehensive collection (Zhang, 2012). Specifically, the database contains 50 genuine subjects (30 test and 20 training

subjects). Three imaging qualities are considered (low, normal and high quality). Fake faces are generated from high quality records of genuine faces. Three fake face attacks are implemented: warped photo attacks, in which face images are printed on paper and warped to simulate motion; Cut photo attacks, in which the printed face photo has also eye cuts to simulate blinking; Video attacks, in which face images are displayed using a mobile device. Each subject contains 12 videos (3 genuine and 9 fake), and the final database contains 600 video clips.

For our evaluation purpose and the different focus of our system (see chapter 1), the cut photo attack has been eliminated and the video attack has been considered to be real. Thus, each subject contains 9 videos (6 genuine and 3 fake) and the final database contains test videos from 30 subjects (270 video clips). The results are represented in Table 3+4 and visualized in Figure 9. A *Precision* of ~95%, a *Mean Accuracy* of ~99% and a *HTER* of ~6% were achieved. From the DET curve in Fig. 8, as a result of the warped motion, one may note that the *FAR* (10%) is higher than the *FRR* (2%).

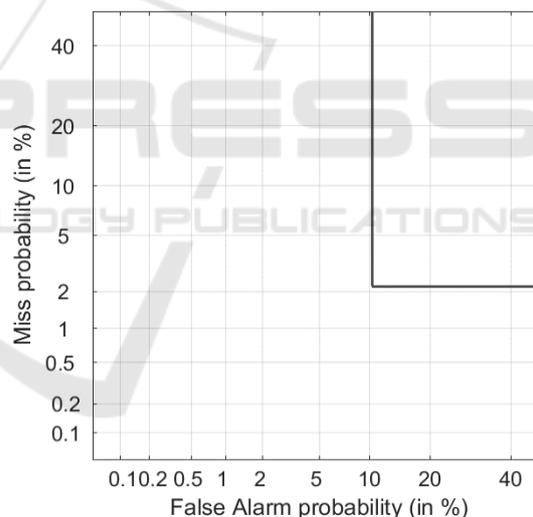


Figure 9: DET curve plotting for the CASIA database.

B) MSU

The MSU face spoof attack database consists of 280 video clips including photo and video attack attempts to 35 clients (Wen et al, 2015). Altogether, there are 280 real-accesses and attack videos captured in one scenario. For our evaluation purpose, as done with the previous database, the video attacks have been considered to be genuine users. Thus, only the printed photo attacks are considered to be fake users. Moreover, 12 videos were removed from the dataset, due to the fact, that the faces were upside down and therefore not relevant for us. In sum 268 (198

genuine, 70 fake) video clips were used in total.

The results are shown in Table 3+4 and graphically represented in Figure 10. As it can be seen, the *FN* rises compared to the CASIA database (~18%). This effect can be explained by short videos without the presence of life signs (no blinking, smiling, speaking) being part of the database.

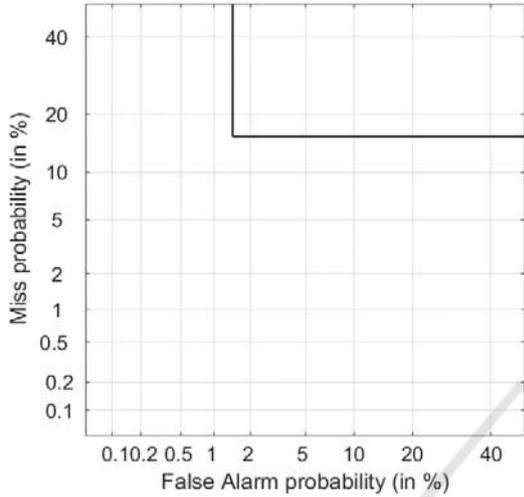


Figure 10: DET curve plotting for the MSU database.

C) IDIAP

The IDIAP face spoofing replay-attack database consists of 1300 video clips of photo and video attack attempts to 50 clients, under different lighting conditions (Chingovska et al, 2012). All videos are generated by either having a real client trying to access a laptop through a built-in webcam or by displaying a photo or a video recording of the client.

For our evaluation purpose, only the test set of video clips, that contains 80 real-accesses and 400 video and photo attacks under different lighting conditions, was used. Results are presented both numerically and graphically in Table 3+4 and Figure 11. Analogical to the MSU database, the *FN* rate is increased (~28%), due to the nonexistence of life signs in many of the video clips.

Table 3: Confusion matrix results of the PAD method.

Database	TN	FN	FP	TP
CASIA	78	4	9	179
MSU	69	31	1	167
IDIAP	172	67	4	234

Table 4: Performance percentage results of the PAD method for the databases CASIA, MSU, IDIAP.

Database	Precision	Recall	FP Rate	FN Rate	Mean Accuracy	HTER
CASIA	95,21%	97,81%	10,34%	2,13%	99,81%	6,27%
MSU	99,40%	84,34%	1,43%	18,45%	88,06%	8,54%
IDIAP	97,73%	71,97%	1,68%	28,15%	85,12%	14,85%

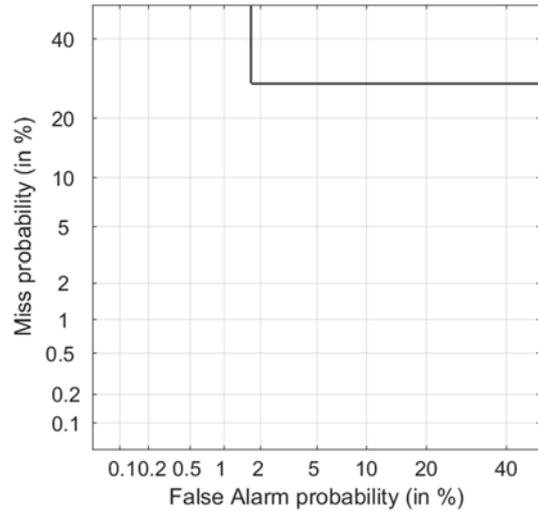


Figure 11: DET curve plotting for the IDIAP database.

D) Comparison of our method

In contrast to the blinking rate, a direct comparison with other PAD techniques in numbers is not as meaningful, due to the non-unified and ambiguous metrics, as well as the fact that our evaluating tests were performed with a slightly different focus, since our aim was to supplement a PPGI monitoring system. Thus, requirements of our aim system slightly varied compared to other projects. For this reason the IDIAP database, for instance, turned out to be more challenging due to the lack of life sign motion.

Although not comparing results in numbers at this point, some qualitative statements can be made. The evaluation results prove the approach to be well suited for our application scenarios. The method was integrated in our online PPGI algorithm as PAD system to prevent false detections. With an average computation time of 0.0037s in Matlab on a standard Windows PC (i5) the method meets the low-cost criteria. Therefore our approach shows its practical importance for face tracking based applications, since it is built on an efficient and resource-saving method. In general, performances below 10% (*HTER*) were achieved, so these good results, compared to state of the art (Wen et al, 2015), prove that the approach is also suitable for other types of applications.

5 CONCLUSIONS

Face detection and tracking are crucial technologies for applications in the fields of security, health care and others. However, such systems are vulnerable to false detections or spoof attacks made by non-real faces using photograph, video or mask attacks. Therefore, PAD strategies are needed to close this gap for systems in face recognition contexts.

In this paper, we introduced a new, effective and low-cost PAD addressing the problem of face anti-spoofing and false detection errors with life sign detection techniques as supplement for a camera-based vital sign monitoring system. Thus, inherent characteristics of a live face like blinking, speaking and smiling were exploited using peak descriptors and cross-correlation coefficients as classifiers for time series analysis. For the classification a sliding time windows of 5 seconds was used.

The presented method has the advantage of being highly secure against 2D image or 3D sculpture spoof attacks, though at a much lower computational cost than traditional techniques (average runtime of 0.0037s in Matlab on a standard Windows PC). This enables the integration of the anti-spoofing method in our PPGI algorithm and possible future porting on embedded systems that use simple, energy-efficient and inexpensive CPU. This would provide a resource-saving biometric method for cars, TV sets and other devices.

Experimental results on three challenging spoofing databases, (CASIA, MSU and IDIAP Replay-Attack) proof, that the proposed PAD algorithm is able to detect spoofing attacks with good accuracy (~85-95%). Moreover, the blinking detector's performance evaluation showed very promising results. We achieved results comparable to the state-of-the-art (99,8% of *Mean Accuracy*) on ZJU datasets and even better results (99,9% of *Mean Accuracy*) on the Talking dataset.

Thus, these results prove the effectiveness of the distinction between genuine and fake faces in scenarios derived from everyday life situations. In particular, the proposed face liveness detection method is well suited to detect the realness of persons in camera based systems aiming to derive signals from a person's face, like vital signs or facial expressions.

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